

# DISTRIBUTED TENSORFLOW\* TRAINING WITH INTEL® NGRAPH LIBRARY ON INTEL® XEON® SCALABLE PROCESSORS

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July 11<sup>th</sup>, 2019

# Outline

- Why and what is nGraph?
- Distributed training architecture on nGraph
- Scaling and convergence results
- Conclusion and next steps

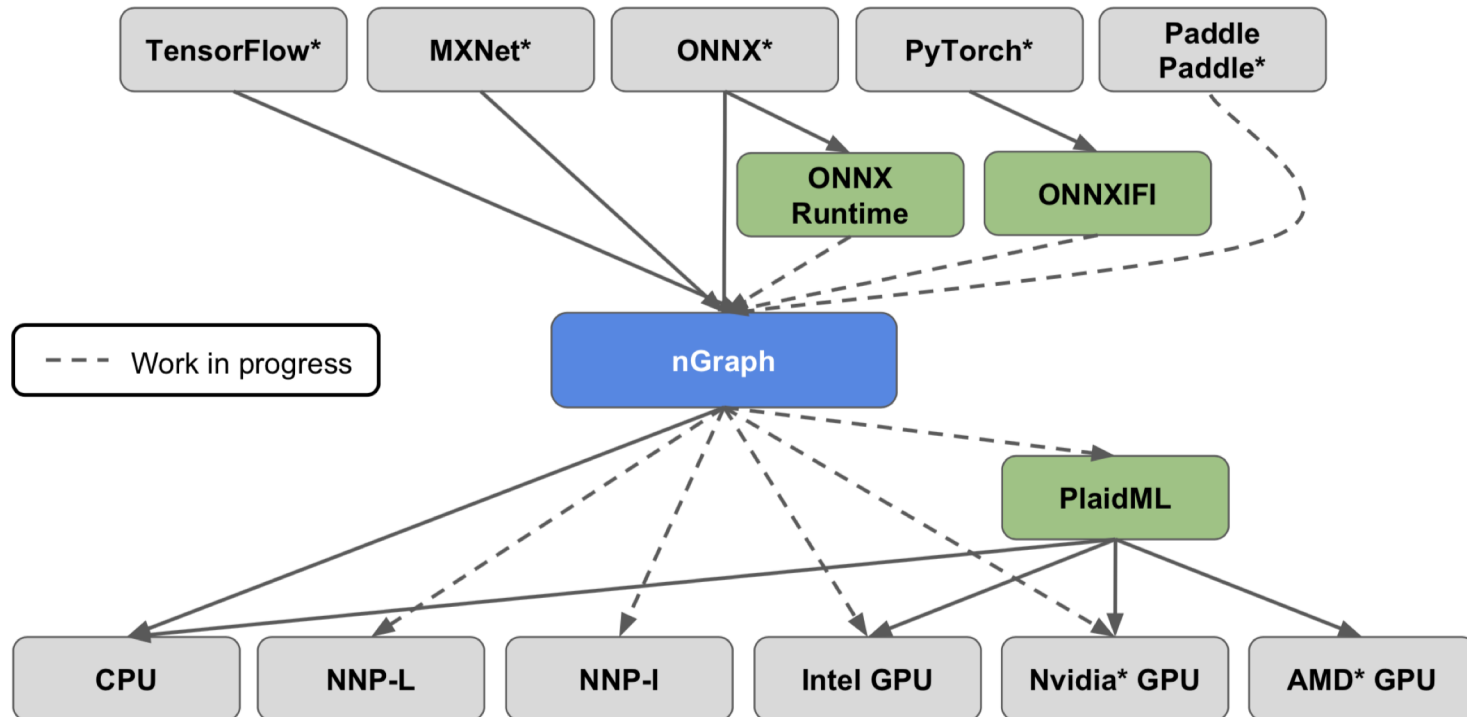
# Why nGraph

<https://vimeo.com/347401000>

Courtesy to AIPG marketing team

Reduces the optimization complexity from  $O(m*n)$  to  $O(m+n)$

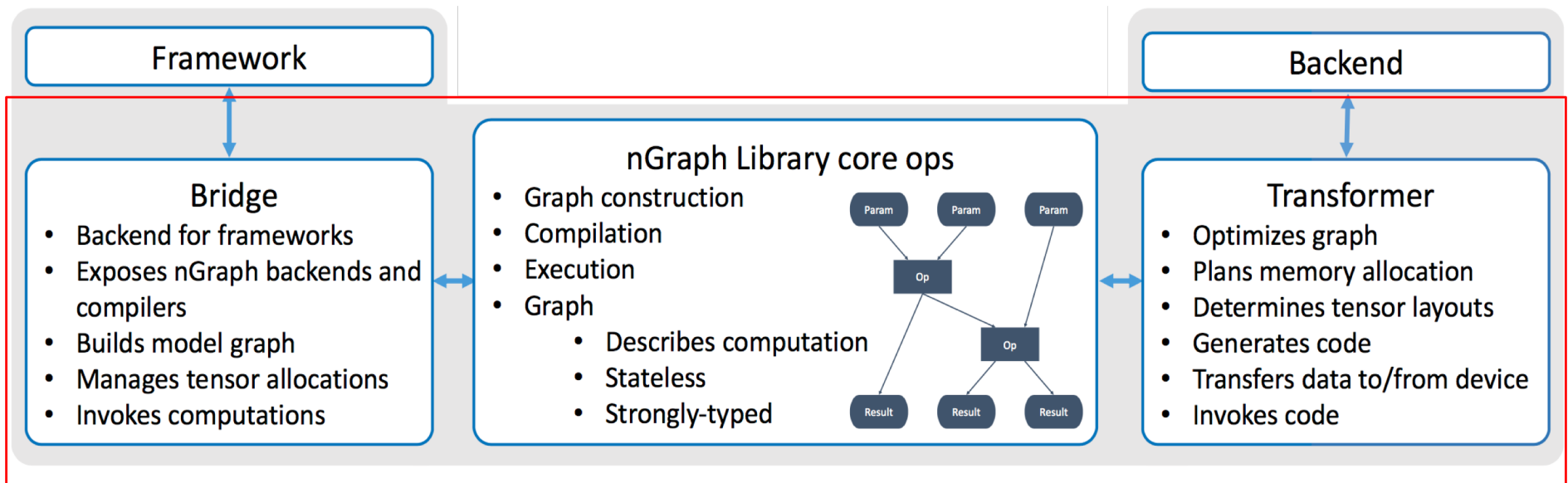
# nGraph - Open source C++ library, compiler & runtime for DL



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# nGraph Stack

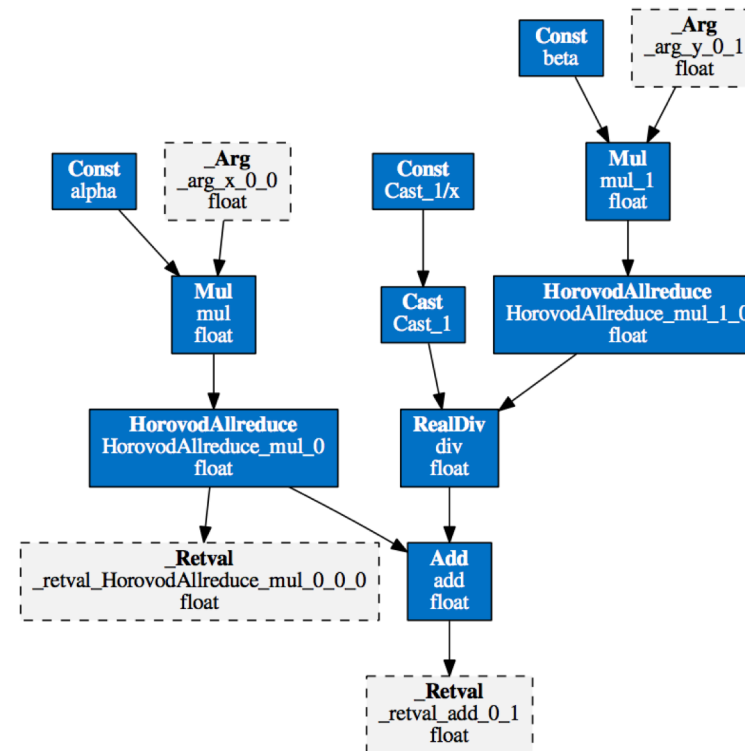


# Easy to use

- Easy to install and use
- Support both training and inference
- Performance is on par or better than the direct optimization
- Minimize the changes from the user side
  - Take Tensorflow as an example
  - Users only need to add the following in their script

```
import ngraph_bridge
```

TensorFlow Graph: Graph Marked for Clustering



# Computing architecture for machine learning tasks

- The ultimate goal is to design a heterogeneous computing system with multiple kinds of processors to gain performance and energy efficiency in handling large-scale machine learning tasks.
- As a first step, we are focusing on distributed training using one architecture during the runtime.
- One goal is to develop generic distributed feature in nGraph which could be easily applied to all the framework platforms without much change from user side.

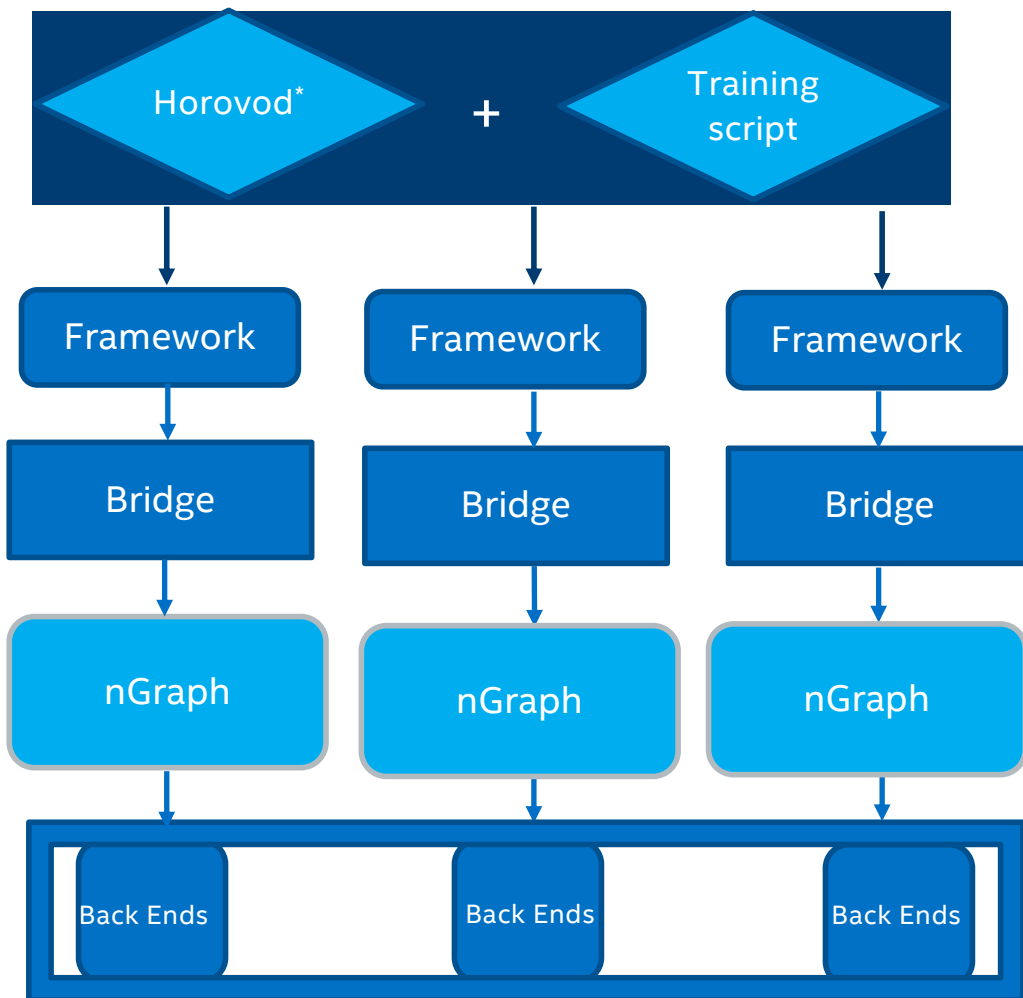
# Data Parallel on nGraph

Each device will have a replica of the training script (graph)

The training data is distributed on each device

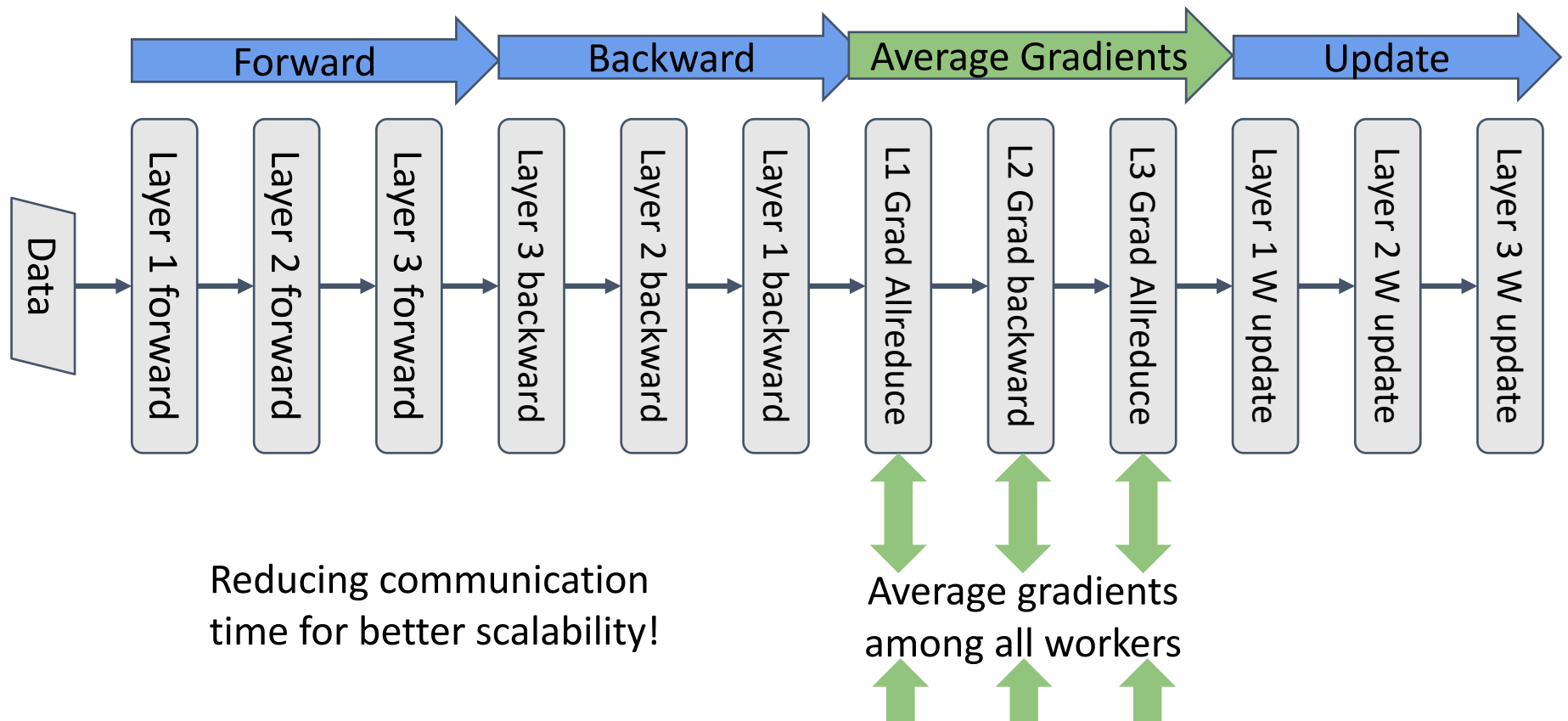
- Each device runs its own data through the model and computes the local gradient
- Gradients on each device will be averaged through a gather-scattering process (allreduce)

The model will be updated with the averaged gradients

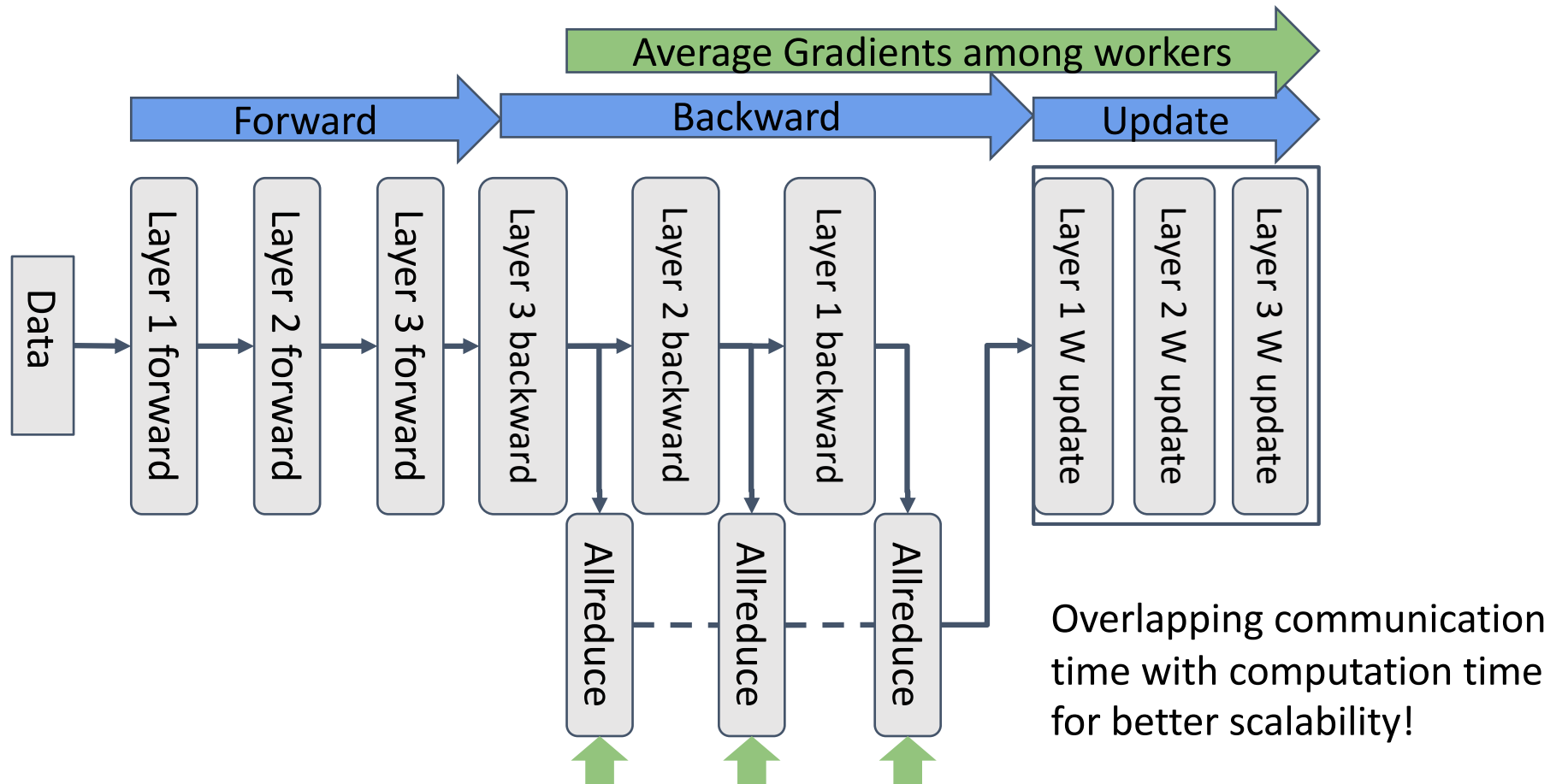




# Synchronous SGD



# Asynchronous SGD



# Horovod\* -- MPI

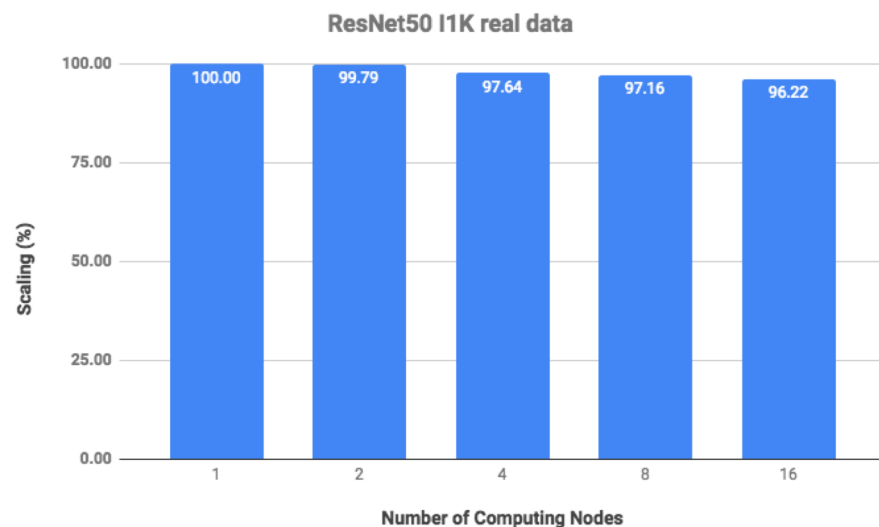
- Horovod\* is a distributed training framework for TensorFlow\*, Keras\*, PyTorch\*, and MxNet\*.
- It utilize the MPI technique for the communication
- The installation requires MPI library and then pip install Horovod\*
- This framework is user friendly and it requires less code change from user side than parameter server does
- Better scaling performance
  - MPI transparently sets up the distributed infrastructure necessary for workers to communicate with each other.
  - The MPI communication coordination implementation reduces the wait time for each device

# Distributed training results

- The distributed model needs to achieve the scaling efficiency from training time to standard top-1/top-5 accuracy and scale up to a large number of nodes.
- The current distributed development in nGraph focuses on main framework: TensorFlow\*, PaddlePaddle\*, and MxNet\*.
- This presentation will only show TensorFlow\* results.
- Data parallel is used for distributed training. The batch size per device keeps the same.

# Performance benchmark with Horovod\*

We have achieved good multi-node scaling in nGraph using Horovod\* by placing the communication op (AllReduce) on Intel® Xeon®



- Single node performs better with 2 processes mapped by socket using mpirun
- >96% scaling up to 16 nodes with Ethernet interconnect
- 16 2S Intel® Xeon® Platinum 8180 CPU nodes RN50 training achieves 15.4x performance gain compared to the single 2S node

## ResNet-50 with Imagenet 1K dataset using Horovod and nGraph TensorFlow

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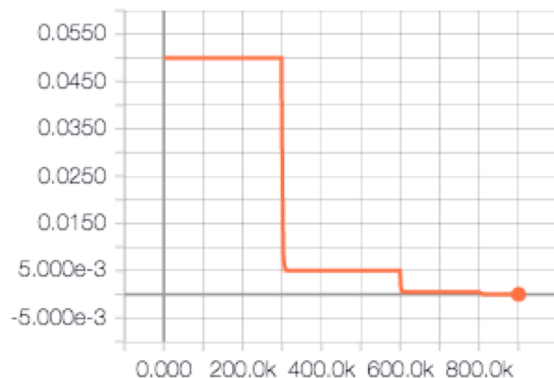
# Convergence test (single node)

Hyper parameter tuning is the key to get convergence to the targeted accuracy for multi-node training

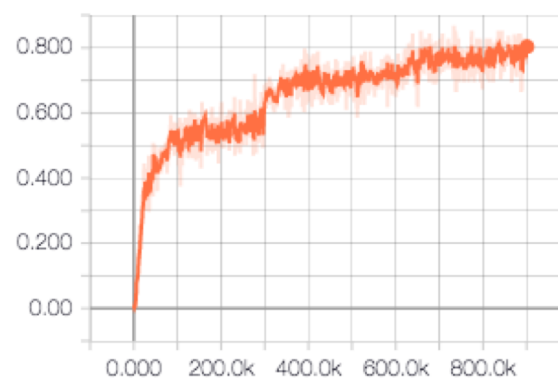
Larger batch size requires larger learning rate ( $lr \propto \text{Total Batch Size}$ )

Take `tf_cnn_benchmark` model script as an example, the validation accuracy @top-1 is 75.5% and accuracy@top-5 is 92.54% at 90 epochs

learning\_rate\_1



top\_1\_accuracy



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# Multi-node convergence for ResNet50 I1K

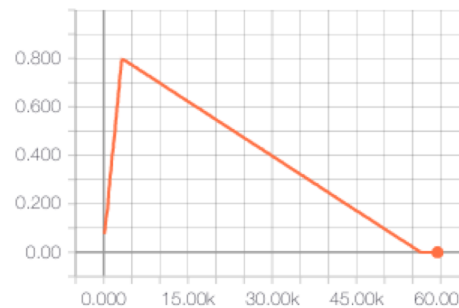
By 90 epochs on 8 2S Intel® Xeon® Platinum 8180 CPU nodes

- 75.5% accuracy@top-1
- 92.5% accuracy@top-5

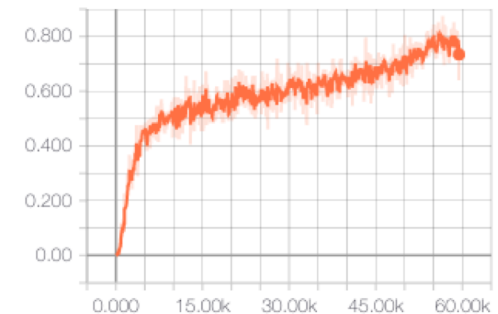
By 90 epochs on 16 2S Intel® Xeon® Platinum 8180 CPU nodes

- 75.0% accuracy@top-1
- 92.3% accuracy@top-5

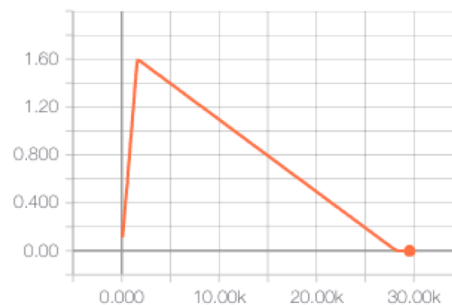
learning\_rate



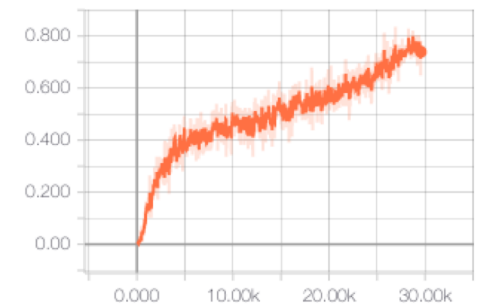
top\_1\_accuracy



learning\_rate



top\_1\_accuracy



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# Conclusion

- Intel® developed open source code nGraph (C++) support distributed training and we have successfully run distributed ResNet50 I1K through nGraph on Intel® Xeon®.
- On multi-node Intel® Xeon® nodes , we have achieved the start-of-art ResNet50 accuracy@top-1 and accuracy@top-5.
- The performance reaches >96% of scaling efficiency up to 16 2s Intel® Xeon® Platinum 8180 CPU nodes.
- Work in progress on scaling nGraph to a large number of cluster nodes and developing model parallel support.



# Configuration Details

Platforms: Intel® Xeon® Platinum 8180 CPU @ 2.50GHz, 2 sockets, 28 cores per socket, Link encap:Ethernet

model repos: <https://github.com/tensorflow/models.git>

Benchmark scripts: <https://github.com/tensorflow/benchmarks.git>

Tensorflow framework: <https://github.com/tensorflow/tensorflow.git>

Ngraph-TF: <https://github.com/NervanaSystems/ngraph-tf.git>

Horovod: <https://github.com/uber/horovod.git>

Run command:

```
export OMP_NUM_THREADS=28 export PYTHONPATH=$PYTHONPATH:<path-to-models>/models
```

```
mpirun --mca btl_tcp_if_include eno1 -np 16 -x LD_LIBRARY_PATH -H skx123,skx124,skx125,skx126, skx127,nervana-skx128,skx129,skx130 -x  
OMP_NUM_THREADS -x PYTHONPATH -cpus-per-proc 28 -map-by socket --oversubscribe --report-bindings python tf_cnn_benchmarks.py --variable_update  
horovod --model=official_resnet50 --batch_size=128 --data_format NCHW --num_intra_threads 28 --num_inter_threads 2 --horovod_device cpu --nodistortions --  
num_epochs=90 --num_warmup_batches=3125 --save_model_secs=625 --mkl=true --data_name=imagenet --data_dir /dataset/TF_ImageNet_latest/ --  
train_dir 8node_resnet50 --datasets_use_prefetch=False --kmp_blocktime=1 --kmp_affinity=granularity=fine,compact,1,0 --eval_interval_secs=625 --  
print_training_accuracy=True --summary_verbosity=2 --benchmark_log_dir=benchmark_logs --optimizer=sgd --save_summaries_steps=20
```

```
mpirun --mca btl_tcp_if_include eno1 -np 32 -x LD_LIBRARY_PATH -H skx117, skx118, skx119,skx120, skx121, skx122, skx123, skx124,skx125, skx126, skx127,  
skx128, skx129, skx130, skx131, skx132 -x OMP_NUM_THREADS -x PYTHONPATH -cpus-per-proc 28 -map-by socket --oversubscribe --report-bindings python  
tf_cnn_benchmarks.py --variable_update horovod --model=official_resnet50 --batch_size=128 --data_format NCHW --num_intra_threads 28 --num_in  
ter_threads 2 --horovod_device cpu --nodistortions --num_epochs=90 --num_warmup_batches=1563 --save_model_secs=313 --mkl=true --  
data_name=imagenet --data_dir /dataset/TF_ImageNet_latest/ --train_dir /mnt/data/langjian/16node_resnet50_accu racy_sgd_90epoch --  
datasets_use_prefetch=False --kmp_blocktime=1 --kmp_affinity=granularity=fine,compact,1,0 --eval_interval_secs=313 --print_training_accuracy=True --  
summary_verbosity=2 --benchmark_log_dir=benchmark_logs --optimizer=sgd - -save_summaries_steps=20
```

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